

The *determinant* of a **matrix** is a number which tells us something about the properties of the matrix. For example, if the matrix represents a 2-dimensional **linear transformation**, then the determinant will tell us the ratio by which areas are scaled, while for a 3-dimensional linear transformation, it will give the volume ratio.

Often the determinant of

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

is written as

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} \text{ or } \det \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

For this 2×2 -matrix, the determinant is $\det A = ad - bc$. In this case the determinant is the area of a parallelogram with sides given by the vectors

$$\begin{pmatrix} a \\ c \end{pmatrix} \text{ and } \begin{pmatrix} b \\ d \end{pmatrix},$$

which is the image of the unit square with sides $\mathbf{i} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ and $\mathbf{j} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$.

For a 3×3 -matrix, we can find the determinant as follows:

$$\begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix} = a \begin{vmatrix} e & f \\ h & i \end{vmatrix} - b \begin{vmatrix} d & f \\ g & i \end{vmatrix} + c \begin{vmatrix} d & e \\ g & h \end{vmatrix}.$$

(This is called the *Laplace expansion* or the *cofactor expansion* of the determinant. This generalises to $n \times n$ -matrices.) In this case, the determinant is the volume of the parallelepiped with edges given by the vectors

$$\begin{pmatrix} a \\ d \\ g \end{pmatrix}, \begin{pmatrix} b \\ e \\ h \end{pmatrix}, \text{ and } \begin{pmatrix} c \\ f \\ i \end{pmatrix},$$

which is the image of the unit cube with sides \mathbf{i} , \mathbf{j} and \mathbf{k} .